Spherical or plane grating

monochromator





It is the task of the monochromator to realise the

pitch movement of four gratings and to guarantee the exchange of the gratings. The gratings are arranged separately in highly precise and stable supports which are equipped with fine adjustment systems under vacuum. The silicon gratings are downwardly oriented and can perform a pitch rotation of approx. 20°. The exact positioning of the grating surface in the pitch axis is important. High-precision hybrid ball bearings will be used as bearing mechanism. For the exchange of the gratings the gratings will travel in a linear slide. An optional pressure mechanism forces the respective active grating against a reference plate, so that a high repeatability of the grating position is achieved.

The pitching movement of the grating system is performed via a translatory movement which is transfered from the outside into the vacuum chamber via a membrane bellow.

The motorization is outside the vacuum, the stepping motors can be combined with harmonic drive gears which will allow very high transmission ratios and thus the necessary angular resolution for the pitching movement. The exchange of the gratings will be performed via atranslatory motion from the outside. The pitch and exchanging positions of the gratings are read via linear and angular encoders, which can be operated in vacuum. The entire grating mechanism is arranged on a very stable base plate which come from the outer main frame. The monochromator frame consists of solid tubes which are welded to the floor base plate. A sputtering ion pump (500 l/s) is used as a vacuum pump.

The vacuum chamber has a diameter of approx. 800 mm and is completely metal-sealed.

All four gratings are fitted with lateral cooling plates. Cooling is performed using water.

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Technical Data.

Gratings Number : Bulk material : Bulk dimension : Shape : Grating fine adjustment : Grating cooling :	4 Silicon 180 x 38 x 35 Spherical / Plane Pitch, Roll, Yaw, Height possible under vacuum yes
Grating pitch drive Stepper motor : Gear : Gear ratio : Vertical range : Vertical movement : Encoder : Encoder resolution : End switch number:	500 steps Harmonic Drive 100 : 1 + 2545 mm relative to the horizontal position 0.00001 mm per full step incremental 50 nm 2 x 2 (active and redundant)
Grating change drive Stepper motor : Gear : Gear ratio : Horizontal range : Horizontal movement : Encoder : Encoder resolution : End switch number:	500 steps Planetary Gear 6 : 1 0 225 mm 0.00033 mm per full step incremental 1μm 2 x 2 (active and redundant)

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